INFORMATION DISTANCE

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ABSTRACT. While Kolmogorov complexity is the accepted absolute measure of information content in an individual finite object, a similarly absolute notion is needed for the information distance between two individual objects, for example, two pictures. We give several natural definitions of a universal information metric, based on length of shortest programs for either ordinary computations or reversible (dissipationless) computations. It turns out that these definitions are equivalent up to an additive logarithmic term. We show that the information distance is a universal cognitive similarity distance. We investigate the maximal correlation of the shortest programs involved, the maximal uncorrelation of programs (a generalization of the Slepian-Wolf theorem of classical information theory), and the density properties of the discrete metric spaces induced by the information distances. A related distance measures the amount of nonreversibility of a computation. Using the physical theory of reversible computation, we give an appropriate (universal, anti-symmetric, and transitive) measure of the thermodynamic work required to transform one object in another object by the most efficient process. Information distance between individual objects is needed in pattern recognition where one wants to express effective notions of "pattern similarity" or "cognitive similarity" between individual objects and in thermodynamics of computation where one wants to analyse the energy dissipation of a computation from a particular input to a particular output.

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1. INTRODUCTION

We write *string* to mean a finite binary string. Other finite objects can be encoded into strings in natural ways. The set of strings is denoted by $\{0,1\}^*$.

The Kolmogorov complexity, or algorithmic entropy, $K(x)$ of a string x is the length of a shortest binary program to compute x on a universal computer (such as a universal Turing machine). Intuitively, $K(x)$ represents the minimal amount of information required to generate x by any effective process, [9]. The conditional Kolmogorov complexity $K(x|y)$ of x relative to y is defined similarly as the length of a shortest program to compute x if y is furnished as an auxiliary input to the computation. The functions $K(\cdot)$ and $K(\cdot|\cdot)$, though defined in terms of a particular machine model, are machine-independent up to an additive constant and acquire an asymptotically universal and absolute character through Church's thesis, from the ability of universal machines to simulate one another and execute any effective process. The Kolmogorov complexity of a string can be viewed as an absolute and objective quantification of the amount of information in it. This leads to a theory of *absolute* information *contents* of *individual* objects in contrast to classic information theory which deals with *average* information *to communicate* objects produced by a *random source*. Since the former theory is much more precise, it is surprising that analogons of theorems in classical information theory hold for Kolmogorov complexity, be it in somewhat weaker form.

Here our goal is to study the question of an "absolute information distance metric" between individual objects. This should be contrasted with an information metric (entropy metric) such as $H(X|Y) + H(Y|X)$ between stochastic sources X and Y. Non-absolute approaches to information distance between individual objects have been studied in a statistical setting, see for example [25] for a notion of empirical information divergence (relative entropy) between two individual sequences. Other approaches include various types of edit-distances between pairs of strings: the minimal number of edit operations from a fixed set required to transform one string in the other string. Similar distances are defined on trees or other data structures. The huge literature on this ranges from pattern matching and cognition to search strategies on internet and computational biology. As an example we mention nearest neighbor interchange distance between evolutionary trees in computational biology, [24, 21]. *A priori* it is not immediate what is the most appropriate *universal* symmetric informational distance between two strings, that is, the minimal quantity of information sufficient to translate between x and y, generating either string effectively from the other. We give evidence that such notions are relevant for pattern recognition, cognitive sciences in general, various application areas, and physics of computation.

Metric. A *distance* function D with nonnegative real values, defined on the Cartesian product $X \times X$ of a set X is called a *metric* on X if for every $x, y, z \in X$:

- $D(x,y) = 0$ iff $x = y$ (the identity axiom);
- $D(x,y) + D(y,z) \geq D(x,z)$ (the triangle inequality);
- $D(x,y) = D(y,x)$ (the symmetry axiom).

A set X provided with a metric is called a *metric space*. For example, every set X has the trivial *discrete metric* $D(x,y) = 0$ if $x = y$ and $D(x,y) = 1$ otherwise. All information distances in this paper are defined on the set $X = \{0,1\}^*$ and satisfy the metric conditions up to an additive constant or logarithmic term while the identity axiom can be obtained by normalizing.

Algorithmic Information Distance. Define the information distance as the length of a shortest binary program that computes x from y as well as computing y from x. Being shortest, such a program should take advantage of any redundancy between the information required to go from x to y and the information required to go from y to x. The program functions in a catalytic capacity in the sense that it is required to transform the input into the output, but itself remains present and unchanged throughout the computation. We would like to know to what extent the information required to compute y from x can be made to overlap with that required to compute x from y. In some simple cases, *complete* overlap can be achieved, so that the same minimal program suffices to compute x from y as to compute y from x. For example if x and y are independent random binary strings of the same length n (up to additive contants $K(x|y) = K(y|x) = n$), then their bitwise exclusive-or $x \oplus y$ serves as a minimal program for both computations. Similarly, if $x = uv$ and $y = vw$ where u, v, and w are independent random strings of the same length, then $u \oplus w$ plus a way to distinguish x from y is a minimal program to compute either string from the other.

Maximal Correlation. Now suppose that more information is required for one of these computations than for the other, say,

$$K(y|x) > K(x|y).$$

Then the minimal programs cannot be made identical because they must be of different sizes. In some cases it is easy to see that the overlap can still be made complete, in the sense that the larger program (for y given x) can be made to contain all the information in the shorter program, as well as some additional information. This is so when x and y are independent random strings of unequal length, for example u and vw above. Then $u \oplus v$ serves as a minimal program for u from vw, and $(u \oplus v)w$ serves as one for vw from u.

A principal result of this paper in Section 3 shows that, up to an additive logarithmic error term, the information required to translate between two strings can be represented in this maximally overlapping way in every case. Namely, let

$$k_1 = K(x|y),\ k_2 = K(y|x),$$
$$l = k_2 - k_1$$

where we assume $k_1 \leq k_2$. Then there is a string q of length $k_1 + K(k_1, k_2)$ and a string d of length l such that q serves as the minimal program both to compute from xd to y and from y to xd. The term $K(k_1, k_2)$ has magnitude $O(\log k_2)$. This means that the information to pass from x to y can always be maximally correlated with the information to get from y to x. It is therefore never the case that a large amount of information is required to get from x to y and a large *but independent* amount of information is required to get from y to x. This demonstrates that

$$E_1(x, y) = \max\{K(y|x), K(x|y)\}$$

equals the length of a shortest program $p := qd$ to compute x from y and y from x, up to a logarithmic additive term.[1] (It is very important here that the time of computation is completely ignored: this is why this result does not contradict the idea of one-way functions.)

The process of going from x to y may be broken into two stages. First, add the string d; second, use the difference program q between xd and y. In the reverse direction, first use q

[1]The situation is analogous to the inverse function theorem of multidimensional analysis. This theorem says that under certain conditions, if we have a vector function $f(x, p)$ then it has an inverse $g(y, p)$ such that in a certain domain, $f(x, p) = y$ holds if and only if $g(y, p) = x$. In the function going from y to x, the parameter p remains the same as in the function going from x to y.

to go from y to xd; second, erase d. Thus the computation from x to y needs both q and d, that is, the program $p = qd$, while the computation from y to x needs only q as program.

Minimal Correlation. The converse of maximal correlation is that in the special case of the shortest programs for going between *independent random* x and y, they can be choosen *completely independent*. For example use y to go from x to y and x to go from y to x. This turns out to hold also in the general case for arbitrary pairs x, y, as will be shown in Theorem 3, but only with respect to an "oracle": a certain constant string that must be in all the conditions. This theorem can be considered a generalization of the Slepian-Wolf Theorem of classical information theory [8].

Universal Cognitive Distance. Section 4 develops an axiomatic theory of "pattern distance" or more generally a "cognitive similarity metric" and argues that the function $E_1(x, y)$ is the most natural way of formalizing a *universal* cognitive distance between x and y. This nonnegative function is 0 iff $x = y$ (rather, its normalized version in Theorem 4 satifies this), it is symmetric, obeys the triangle inequality to within an additive constant, and is minimal among the class of distance functions that are computable in a weak sense and satisfy a normalization constraint limiting the number of distinct strings y within a given distance of any x. It uncovers all effective similarities between two individual objects.

Information Distance for Reversible Computation. Up till now we have considered ordinary computations, but if one insists that the computation be performed *reversibly*, that is by a machine whose transition function is one-to-one [18, 3], then the full program $p = qd$ above is needed to perform the computation in either direction. This is because reversible computers cannot get rid of unwanted information simply by erasing it as ordinary irreversible computers do. If they are to get rid of unwanted information at all, they must cancel it against equivalent information already present elsewhere in the computer. Reversible computations are discussed in Section 5 where we define a reversible distance $E_2(x, y) = KR(x|y) = KR(y|x)$, representing the amount of information required to program a reversible computation from x to y (which by definition is the reverse of the computation from y to x). The E_2 distance is equal within an additive constant to the length of the conversion program $p = qd$ considered above, and so is at most greater by an additive logarithmic term than the optimal distance E_1. It is also a metric. The reversible program functions again in a catalytic manner.

Hence, three very different definitions arising from different backgrounds identify up to logarithmic additive terms the same notion of information distance and corresponding metric. It is compelling to believe that our intuitive notions are adequately formalized by this universal and absolute notion of information metric.

Minimal Number of Irreversible Operations. Section 6 considers reversible computations where the program is not catalytic but in which additional information p (like a program) besides x is consumed, and additional information q (like garbage) besides y is generated and irreversibly erased. The sum of these amounts of information, defined as distance $E_3(x, y)$, represents the minimal number of irreversible bit operations in an otherwise reversible computation from x to y in which the program is not retained. It is shown to be equal to within a logarithmic term to Zurek's sum metric $K(y|x) + K(x|y)$, which is typically larger than our proposed optimal metric E_1 because of the redundancy between p and q. But using the program involved in E_1 we both consume it and are left with it at the end of the computation, accounting for $2E_1(x, y)$ irreversible bit operations, which is typically larger than $E_3(x, y)$. Up to additive logarithmic terms $E_1(x, y) \leq E_3(x, y) \leq 2E_1(x, y)$.

If the total computation time is limited then the total number of irreversible bit operations will rise. Resource-bounded versions of $E_3(\cdot,\cdot)$ are studied in [20].

Thermodynamic Work. Section 8 considers the problem of defining a thermodynamic entropy *cost* of transforming x into y, and argues that it ought to be an anti-symmetric, transitive function, in contrast to the informational metrics which are symmetric. Landauer's principle connecting logical and physical irreversibility is invoked to argue in favor of $K(x) - K(y)$ as the appropriate (universal, anti-symmetric, and transitive) measure of the thermodynamic work required to transform x into y by the most efficient process.

Density in Information Metric Spaces. Section 9 investigates the densities induced by the optimal and sum information metrics. That is, how many objects are there within a given distance of a given object. Such properties can also be viewed as "dimensional" properties. They will govern many future applications of information distances.

2. Kolmogorov Complexity

Let $l(p)$ denote the length of the binary string p. Let $\#S$ denote the number of elements of set S. We give some definitions and basic properties of Kolmogorov complexity. For all details and attributions we refer to [22]. There one can also find the basic notions of computability theory and Turing machines. The "symmetry of information" property in Equation 5 is from [13]. It refines an earlier version in [28] relating to the original Kolmogorov complexity of [9].

Definition 2.1. We say that a real-valued function $f(x,y)$ over strings or natural numbers x,y is *upper semicomputable* if the set of triples

$$\{\,(x,y,d) : f(x,y) < d, \text{ with } d \text{ rational}\,\}$$

is recursively enumerable. A function f is *lower semicomputable* if $-f$ is upper semicomputable.

Definition 2.2. A *prefix set*, or prefix-free code, or prefix code, is a set of strings such that no member is a prefix of any other member. A prefix set which is the domain of a partial recursive function (set of halting programs for a Turing machine) is a special type of prefix code called a *self-delimiting* code because there is an effective procedure which reading left-to-right determines where a code word ends without reading past the last symbol. A one-to-one function with a range that is a self-delimiting code will also be called a self-delimiting code.

We can map $\{0,1\}^*$ one-to-one onto the natural numbers by associating each string with its index in the length-increasing lexicographical ordering

$$(\epsilon,0),(0,1),(1,2),(00,3),(01,4),(10,5),(11,6),\ldots, \tag{1}$$

where ϵ denotes the empty word, that is, $l(\epsilon) = 0$. This way we have a binary representation for the natural numbers that is different from the standard binary representation. It is convenient not to distinguish between the first and second element of the same pair, and call them "string" or "number" arbitrarily. As an example, we have $l(7) = 00$. A simple self-delimiting code we use throughout is obtained by reserving one symbol, say 0, as a stop sign and encoding a natural number x as 1^x0. We can prefix an object with its length and iterate this idea to obtain ever shorter codes:

$$\lambda_i(x) = \begin{cases} 1^x0 & \text{for } i = 0, \\ \lambda_{i-1}(l(x))x & \text{for } i > 0. \end{cases} \tag{2}$$

Thus, $\lambda_1(x) = 1^{l(x)}0x$ and has length $l(\lambda_1(x)) = 2l(x)+1$; $\lambda_2(x) = \lambda_1(l(x))x$ and has length $l(\lambda_2(x)) = l(x) + 2l(l(x)) + 1$. From now on, we will denote by $\stackrel{+}{<}$ an inequality to within an additive constant, and by $\stackrel{+}{=}$ the situation when both $\stackrel{+}{<}$ and $\stackrel{+}{>}$ hold. We will also use $\stackrel{\log}{<}$ to denote an inequality to within an additive logarithmic term, and $\stackrel{\log}{=}$ to denote the situation when both $\stackrel{\log}{<}$ and $\stackrel{\log}{>}$ hold. Using this notation we have for example

$$l(\lambda_3(x)) \stackrel{+}{<} l(x) + \log l(x) + 2\log\log l(x).$$

Define the pairing function

$$\langle x, y\rangle = \lambda_2(x)y \tag{3}$$

with inverses $\langle\cdot\rangle_1, \langle\cdot\rangle_2$. A partial recursive function $F(p,x)$ is called *self-delimiting* if for each x, $\{\, p : F(p,x) < \infty \,\}$ is a self-delimiting code. ("$F(p,x) < \infty$" is shorthand for "there is a y such that $F(p,x) = y$.") The argument p is called a *self-delimiting program* for $y := F(p,x)$ from x, because, owing to the self-delimiting property, no punctuation is required to tell the machine where p ends and the input to the machine can be simply the concatenation px.

Remark 2.3. Our results do not depend substantially on the use of self-delimiting programs but for our purpose this form of the theory of Kolmogorov complexity is cleaner and easier to use. For example, the simplicity of the normalization property in Section 4 depends on the self-delimiting property. ♢

Remark 2.4. Consider a multi-tape Turing machine M with a distinguished semi-infinite tape called the *program tape*. The program tape's head begins scanning the leftmost square of the program. There is also an input tape and, possibly, a separate output tape and work tapes. We say that M computes the partial function $F(p,x)$ by a *self-delimiting computation* if for all p and x for which $F(p,x)$ is defined:

- M with program p and input x halts with output $F(p,x)$ written on the output tape.
- The program tape head scans all of p but not beyond p.

A partial recursive function is self-delimiting if and only if there is a self-delimiting computation for it. A Turing machine performing a self-delimiting computation is called a *self-delimiting Turing machine*. ♢

In what follows, informally, we will often call a self-delimiting partial recursive function F a *prefix machine* or *self-delimiting machine* even though it is only the function computed by such a machine.

Definition 2.5. The *conditional descriptional complexity*, (the "self-delimiting" version) $K_F(y|x)$ of y with condition x, with respect to the machine F is defined by

$$K_F(y|x) := \min\{l(p) : F(p,x) = y\},$$

or ∞ if such p do not exist. There is a prefix machine U (the universal self-delimiting Turing machine) with the property that for every other prefix machine F there is an additive constant c_F such that for all x, y

$$K_U(y|x) \le K_F(y|x) + c_F.$$

(A stronger property that is satisfied by many universal machines U is that for all F there is a string s_F such that for all x, y, p we have $U(s_F p, x) = F(p,x)$, from which the stated

property follows immediately.) Since c_F depends on F but not on x, y such a prefix machine U will be called *optimal* or *universal*. We fix such an optimal machine U as reference, write

$$K(y|x) := K_U(y|x)$$

and call $K(y|x)$ the conditional *Kolmogorov complexity* of y with respect to x. The unconditional Kolmogorov complexity of y is defined as $K(y) := K(y|\epsilon)$ where ϵ is the empty word.

We give a useful characterization of $K(y|x)$. It is easy to see that $K(y|x)$ is an upper semicomputable function with the property that for each x we have

$$\sum_y 2^{-K(y|x)} \leq 1. \tag{4}$$

Namely, for each x the set of $K(y|x)$'s is a subset of the length set of a prefix-code. Therefore property 4 is a consequence of the so-called Kraft inequality. It is an important fact that the function $K(y|x)$ is minimal with respect to the normalization property 4:

Lemma 2.6. *For* every *upper semicomputable function $f(x, y)$ satisfying $\sum_y 2^{-f(x,y)} \leq 1$ we have $K(y|x) \stackrel{+}{<} f(x, y)$.*

A prominent example of such a function is the *algorithmic entropy*

$$H(y|x) := -\log \sum_{p:U(p,x)=y} 2^{-l(p)}.$$

Since $K(y|x)$ is the length of the shortest program p such that $U(p, x) = y$ we have $K(y|x) \geq H(y|x)$, and because $H(y|x)$ is upper semicomputable and satisfies $\sum_y 2^{-H(y|x)} \leq 1$ (by the Kraft inequality) we have $K(y|x) \stackrel{+}{<} H(y|x)$. Together this shows that $H(y|x) \stackrel{+}{=} K(y|x)$ (almost all the entropy is concentrated in the shortest program).

The functions $\langle x, y, z\rangle$, etc. are defined with the help of $\langle x, y\rangle$ in any of the usual ways. We introduce the notation

$$K(x, y) = K(\langle x, y\rangle),\ K(x|y, z) = K(x|\langle y, z\rangle),$$

etc. Kolmogorov complexity has the following addition property:

$$K(x, y) \stackrel{+}{=} K(x) + K(y|x, K(x)). \tag{5}$$

Ignoring for a moment the term $K(x)$ in the condition of the second term of the right-hand side, this property says, analogously to the corresponding property of information-theoretic entropy, that the information content of the pair (x, y) is equal to the information content of x plus the information needed to restore y from x.

The *mutual information* between x and y is the quantity

$$I(x : y) = K(x) + K(y) - K(x, y). \tag{6}$$

This is the algorithmic counterpart of the mutual information between two random variables $I(X : Y) = H(X) + H(Y) - H(X, Y)$. Because of the conditional $K(x)$ term in Equation 5, the usual relation between conditional and mutual information holds only to within a logarithmic error term (denoting $x^* := \langle x, K(x)\rangle$):

$$\begin{aligned} I(x : y) &\stackrel{+}{=} K(x) - K(x|y^*) \stackrel{+}{=} K(y) - K(y|x^*) \\ &= K(x) - K(x|y) + O(\log(K(y)) = K(y) - K(y|x) + O(\log(K(x)). \end{aligned}$$

Thus, within logarithmic error, $I(x : y)$ represents both the information in y about x and that in x about y. We consider x and y to be "independent" whenever $I(x : y)$ is (nearly) zero.

Mutual information should not be confused with "common information." Informally, we can say that a string z contains information common in x and y if both $K(z|x)$ and $K(z|y)$ are small. If this notion is made precise it turns out that common information is can be very low even if mutual information is large [12].

3. MAX DISTANCE

In line with the identification of the Kolmogorov complexity $K(x)$ as the information content of x, [9], we define the information distance between x and y as the length of the shortest program that converts x to y and y to x. The program itself is retained before, during, and after the computation. This can be made formal as follows. For a partial recursive function F computed by a prefix (self-delimiting) Turing machine, let

$$E_F(x,y) := \min\{l(p) : F(p,x) = y,\ F(p,y) = x\}.$$

There is a universal prefix machine U (for example the reference machine in Definition 2.5) such that for every partial recursive prefix function F and all x, y

$$E_U(x,y) \leq E_F(x,y) + c_F,$$

where c_F is a constant that depends on F but not on x and y. For each two universal prefix machines U and U', we have for all x, y that $|E_U(x,y) - E_{U'}(x,y)| \leq c$, with c a constant depending on U and U' but not on x and y. Therefore, with U the reference universal prefix machine U of Definition 2.5 we define

$$E_0(x,y) := \min\{l(p) : U(p,x) = y,\ U(p,y) = x\}.$$

Then $E_0(\cdot,\cdot)$ is the universal effective information distance which is clearly optimal and symmetric, and will be shown to satisfy the triangle inequality. We are interested in the precise expression for E_0.

3.1. **Maximum overlap.** The conditional complexity $K(y|x)$ itself is unsuitable as information distance because it is unsymmetric: $K(\epsilon|x)$, where ϵ is the empty string, is small for all x, yet intuitively a long random string x is not close to the empty string. The asymmetry of the conditional complexity $K(x|y)$ can be remedied by defining the informational distance between x and y to be the sum of the relative complexities, $K(y|x) + K(x|y)$. The resulting metric will overestimate the information required to translate between x and y in case there is some redundancy between the information required to get from x to y and the information required to get from y to x.

This suggests investigating to what extent the information required to compute x from y can be made to overlap with that required to compute y from x. In some simple cases, it is easy to see how complete overlap can be achieved, so that the same minimal program suffices to compute x from y as to compute y from x. A brief discussion of this and an outline of the results to follow were given in Section 1.

Definition 3.1. The *max distance* E_1 between x and y is defined by

$$E_1(x,y) := \max\{K(x|y), K(y|x)\}.$$

By definition of Kolmogorov complexity, every program p that computes y from x and also computes x from y satisfies $l(p) \geq E_1(x,y)$, that is,

$$E_0(x,y) \geq E_1(x,y). \tag{7}$$

In Theorem 1 we show that this relation also holds the other way: $E_0(x,y) \leq E_1(x,y)$ up to an additive logarithmic term. Moreover, the information to compute from x to y can always be maximally correlated with the information to compute from y to x. It is therefore never the case that a large amount of information is required to get from x to y and a large *but independent* amount of information is required to get from y to x.

Theorem 1 (Conversion)**.** *Let $K(x|y) = k_1$ and $K(y|x) = k_2$, and $l = k_2 - k_1 \geq 0$. There is a string d of length l and a string q of length*

$$k_1 + K(k_1, k_2) + O(1)$$

such that $U(q, xd) = y$ and $U(q, y) = xd$.

Proof. Given k_1, k_2, we can enumerate the set $S = \{(x,y) : K(x|y) \leq k_1, K(y|x) \leq k_2\}$. Without loss of generality, assume that S is enumerated without repetition, and with witnesses of length exactly k_1 and k_2. Now consider a dynamic graph $G = (V, E)$ where V is the set of binary strings, and E is a dynamically growing set of edges that starts out empty.

Whenever a pair (x,y) is enumerated, we add an edge $e = \{xd, y\}$ to E. Here, d is chosen to be the $(i2^{-k_1})$th binary string of length l, where i is the number of times we have enumerated a pair with x as the first element. So the first 2^{k_1} times we enumerate a pair $(x,\cdot)$ we choose $d = 0^l$, for the next 2^{k_1} times we choose $d = 0^{l-1}1$, etc. The condition $K(y|x) \leq k_2$ implies that $i < 2^{k_2}$ hence $i2^{-k_1} < 2^l$, so this choice is well-defined.

In addition, we "color" edge e with a binary string of length $k_1 + 1$. Call two edges *adjacent* if they have a common endpoint. If c is the minimum color not yet appearing on any edge adjacent to either xd or y, then e is colored c. Since the degree of every node is bounded by 2^{k_1} (when acting as an xd) plus 2^{k_1} (when acting as a y), a color is always available.

A *matching* is a maximal set of nonadjacent edges. Note that the colors partition E into at most 2^{k_1+1} matchings, since no edges of the same color are ever adjacent. Since the pair (x,y) in the statement of the theorem is necessarily enumerated, there is some d of length l and color c such that the edge $\{xd, y\}$ is added to E with color c.

Knowing k_1, k_2, c and either of the nodes xd or y, one can dynamically reconstruct G, find the unique c-colored edge adjacent to this node, and output the neighbour. Therefore, a self-delimiting program q of size $K(k_1, k_2) + k_1 + O(1)$ suffices to compute in either direction between xd and y. □

The theorem states that $K(y|xd, q), K(xd|y, q) \stackrel{+}{=} 0$. It may be called the *Conversion Theorem* since it asserts the existence of a difference string q that converts both ways between xd and y and at least one of these conversions is optimal. If $k_1 = k_2$, then $d = \epsilon$ and the conversion is optimal in both directions.

Theorem 2. *Assume the notation above. Then, with $\stackrel{\log}{=}$ denoting equality up to additive logarithmic terms:*

$$E_0(xd, y) \stackrel{\log}{=} E_1(xd, y) \ (\stackrel{\log}{=} l(q))$$
$$E_0(x, y) \stackrel{\log}{=} E_1(x, y) \ (\stackrel{\log}{=} l(qd)).$$

Proof. (First displayed equation) Assume the notation and proof of Theorem 1. First note that $l(q) \stackrel{\log}{=} E_1(xd, y)$. Moreover, q computes between xd and y in both directions and therefore $l(q) \geq E_0(xd, y)$ by the minimality of $E_0(\cdot, \cdot)$. Hence $E_1(xd, y) \stackrel{\log}{>} E_0(xd, y)$. Together with Equation 7 this shows the first displayed equation holds.

(Second displayed equation) This requires an extra argument because the program $p := qd$ is not yet a program to compute between x and y in both directions. Namely, an input x' can be either x or y in the above proof. Given q, d the program also needs to know whether q should compute from $x'd$ to some y' or from x' to some $y''d$. This problem is resolved by adding a means to distinguish between x and y: With x', y', y'' as above we just add an $O(1)$ bit prefix to p stating whether it computes from x' to y' or from x' to y'' using the string order (as in Equation 1) to express these options. By a similar argument as in the previous case we now obtain the second displayed equation. □

Remark 3.2. The same proofs work for the non-self-delimiting Kolmogorov complexity as in [9] and would also give rise to a logarithmic correction term in the theorem. ♢

Remark 3.3. The difference program $p = qd$ in the above theorem is independent of x in the sense that the mutual information $I(p : x)$ as defined in Equation 6 is nearly 0. This follows from $K(x) + K(p) = K(x, y) + O(\log K(x, y))$ (use Equation 5 with $K(y|x) = K(p)$). The program p is at the same time completely dependent on the pair (x, y).

If $k_1 = k_2$ then $d = \epsilon$ and $p = q$. Then $p = q$ is a conversion program from x to y and from y to x and it is both independent of x and independent of y, that is, $I(p : x), I(p : y)$ are both nearly 0. The program p is at the same time completely dependent on the pair (x, y). ♢

Remark 3.4. Remark (Mutual Information Formulation) Let us reformulate the result of this section in terms of mutual information as defined in Equation 6. Let p be a shortest program transforming x to y and let q be a shortest program transforming y to x. We have shown that p and q can depend on each other as much as possible: the mutual information in p and q is maximal: $I(p : q) = \min\{K(p), K(q)\}$ up to an additive $O(\log K(x, y))$ term. ♢

3.2. **Minimum overlap.** This section can be skipped at first reading; the material is difficult and it is not used in the remainder of the paper. For a pair x, y of strings, we found that shortest program p converting x into y and q converting y into x can be made to overlap maximally. In Remark 3.4 this result is formulated in terms of mutual information. The opposite question is whether p and q can always be made completely *independent*, that is, can we choose p and q such that $I(p : q) = 0$? That is, is it true that for every x, y there are p, q such that $K(p) = K(y|x)$, $K(q) = K(x|y)$, $I(p : q) = 0$, $U(p, x) = y$, $U(q, y) = x$, where the first three equalities hold up to an additive $O(\log K(x, y))$ term. This is evidently true in case x and y are random with respect to one another, that is, $K(x|y) \geq l(x)$ and $K(y|x) \geq l(y)$. Namely, without loss of generality let $y = uv$ with $l(u) = l(x)$. We can choose $p := (x \oplus u)v$ as a shortest program that computes from x to y and $q := x \oplus u$ as a shortest program that computes from y to x, and therefore obtain maximum overlap $I(p : q) = \min\{l(p), l(q)\}$. However, we can also choose shortest programs $p := y$ and $q := x$ to realize minimum overlap $I(p : q) = 0$. The question arises whether we can *always* choose p, q with $I(p : q) = 0$ even when x and y are not random with respect to one another.

Remark 3.5. N.K. Vereshchagin suggested replacing "$I(p : q) = 0$" (that is, $K(p, q) = K(p) + K(q)$) by "$K(q|x) = 0, K(p|y) = 0$," everything up to an additive $O(\log K(x, y))$ term. Then

an affirmative answer to the latter question would imply an affirmative answer to the former question. ♢

Here we study a related but formally different question: replace the condition "$I(p : q) = 0$" by "p is a function of only y" and "q is a function of only x." Note that when this new condition is satisfied it can still happen that $I(p : q) > 0$. We may choose to ignore the latter type of mutual information.

We show that for every pair of integers $k_1, k_2 \geq 0$ there exists a function f with $K(f) = k_1 + k_2 + O(\log(k_1 + k_2))$ such that for every x, y such that $K(x) \leq k_1, K(y|x) \leq k_2$ we have $K(y|x, f(y), f) = O(\log(k_1 + k_2))$ and $l(f(y)) \approx k_2$, that is, $f(y)$ has about k_2 bits and suffices together with a description of f itself to restore y from every x from which this is possible using this many bits. Moreover, there is no significantly simpler function f, say $K(f|y) \ll \min\{k_1, k_2\}$, with this property.

Let us amplify the meaning of this for the question of the conversion programs having low mutual information. First we need some terminology. When we say that f is a *simple function* of y we mean that $K(f|y)$ is small.

Suppose we have a minimal program p, of length k_2, converting x to y and a minimal program q of length k_1 converting y to x. It is easy to see, just as in Remark 3.3 above that y is independent of q. Also, any simple function of y is independent of q. So, if p is a simple function of y, then it is independent of q. The question whether p can be made a simple function of y is interesting in itself since it would be a generalization of the Slepian-Wolf Theorem (see [8]). And it sounds no less counterintuitive at first than that theorem. If it were true then for *each* y there is a k_2-bit program p such that for *every* x satisfying $K(y|x) \leq k_2$, we can reconstruct y from the pair (x, p). As stated already, we will show that p can be made a *function* of y independent of x; but we will also show that p *cannot* be made a *simple* function of y.

Before proceeding with the formal statement and proof we introduce a combinatorial lemma. In a context where a partition $V = \bigcup_j V_j$ of a set V is called a coloring we say that two elements have *the same color* if they belong to the same set V_j.

Lemma 3.6. *Coloring Lemma On a set V, let us be given a set system with M sets S_i (possibly overlapping) of size at most N each. For $B > 0$, a B-*coloring *of this system is a partition $V = \bigcup_j V_j$ such that $\#(S_i \bigcap V_j) \leq B$ for every i, j, that is, there are at most B points of the same color in a set S_i. There is a B-coloring with not more colors than*

$$(N/B)e(MN)^{1/B}.$$

Remark 3.7. Notice that N/B colors are trivially required (and suffice if the S_i's are pairwise disjoint). ♢

Proof. If $B = N$ then one color is enough, so assume $B < N$. Let us try to color with nN/B colors and then see what choice of n satisfies our needs. We choose the color of each element of V independently, with a uniform distribution among the given number of colors, with probability $p = B/(nN)$. For each i, j, we can upperbound the probability that $\#(S_i \bigcap V_j) > B$, using the Chernoff bound (see e.g. [8]) for large deviations in the law of large numbers. In application to the present case, this bound says that if in an experiment of N coin-tosses, the success probability is p then for every $p' > p$, the probability that there are more than Np' successes is at most e^{cN} with

$$c = p' \ln \frac{p}{p'} + (1 - p') \ln \frac{1 - p}{1 - p'}.$$

We apply this bound with $p = B/(nN)$ and $p' = B/N$. Now MNe^{cN} upperbounds the probability that the random coloring is not a B-coloring. Let us see what choice of n makes this bound less than 1.

Estimating the second term of the right-hand side above by $\ln x \leq x - 1$, it is at most $p' - p < p'$, hence $c < p'(\ln(p/p') + 1) = (B/N)(-\ln n + 1)$. Now the condition $MNe^{cN} < 1$ turns into $\ln(MN) + Nc < 0$. Substituting the above estimate for c, we get a stronger condition $\ln(MN) + B \leq B \ln n$, satisfied by $\ln n = (\ln(MN))/B + 1$. □

Theorem 3.

(i) *There is a recursive function R such that for every pair of integers $k_1, k_2 > 0$ there is an integer m with $\log m \leq k_1 + k_2$ and an integer b with $b \stackrel{+}{<} \log(k_1 + k_2) + 2\log\log(k_1 + k_2)$ such that for all x, y with $K(x) \leq k_1$ and $K(y|x) \leq k_2$*

$$K(y|x, f(y), m) \leq b,$$

where $f(y) := R(k_1, k_2, m, y)$ with $l(f(y)) \stackrel{+}{<} k_2$.

(ii) *Using the notation in* (i)*, even allowing for much larger b we cannot significantly eliminate the conditional information m required in* (i)*: If b satisfies*

$$0 \leq b < k_1 - 5\log(k_1 + k_2), \tag{8}$$

then every m satisfying the conditions in (i) *also satisfies*

$$l(m) \geq k_2 - b - 5\log(k_1 + k_2).$$

Remark 3.8. Thus, the extra information in y needed in addition to x to restore y can be made a function $f(y)$ of just y, and its minimality implies that it will be essentially independent of x. However, there is a catch: it is indispensible for these results that certain fixed oracle string m describing how to compute f is also used in the transformations. The role of this oracle string is to make the complexity function computable over the set of strings of interest. ♢

Remark 3.9. If also $K(y) \leq k_2$ then the theorem holds symmetrically in x and y. This is the sense in which the shortest programs $f(y)$ and $f(x)$, converting x into y and y into x, can be made "non-overlapping": they will be independent of the strings they convert *from*. ♢

Proof. (i): We first show the existence of R and m with the above properties. As in the proof of Theorem 1, let $G = (V, E)$ be a graph with the node set $V \subseteq \{0,1\}^*$ and E consisting of those edges (x, y) with $K(x) \leq k_1$ and $K(y|x) \leq k_2$. Let

$$\begin{aligned} M &= 2^{k_1},\ N = 2^{k_2}; \\ S_x &= \{\, y : (x, y) \in E \,\}; \\ B &= k_1 + k_2; \\ m &= \#E. \end{aligned}$$

Then $\#S_x \leq N$, and the number of $x's$ with nonempty S_x is at most M. According to the Coloring Lemma 3.6, there is a B-coloring of the M sets S_x with at most

$$(N/B)e(MN)^{1/B} = 2eN/B \tag{9}$$

colors. Let R be a recursive function computing a color $f(y) = R(k_1, k_2, m, y)$. Using the numbers k_1, k_2, m it reconstructs the graph G. Then it finds (if there is no better way, by exhaustive search) a B-coloring of the S_x's set system. Finally, it outputs the color of y.

Let us estimate $K(y|x, f(y), m)$. Without loss of generality we can assume that the representation of $m \leq 2^{k_1+k_2}$ is padded up to length exactly $k_1 + k_2$. The logarithm of the number of colors is $\stackrel{+}{<} k_2 - \log(k_1 + k_2)$ so with padding we can represent color $f(y)$ by a string of precisely that length. Therefore, we can retrieve k_1, k_2 from the representations of m and $f(y)$ in the conditional. Now for every $y \in S_x$, if we are given k_1, k_2, m, x, and $f(y)$ then we can list the set of all y's in S_x with color $f(y)$. Since the size of this list is at most B, the program to determine y in it needs only the number of y in the enumeration, with a self-delimiting code of length $l(\lambda_2(B)) \stackrel{+}{<} \log(k_1 + k_2) + 2\log\log(k_1 + k_2)$ with λ_2 as in Definition 2.

(ii): Suppose that there is a number m with the desired properties with representation length

$$l(m) < k_2 - b - 5\log(k_1 + k_2), \tag{10}$$

and b satisfies 8. We will arrive from here at a contradiction. First note that the number of y's satisfying $K(y|x) \leq k_2$ for some x with $K(x) \leq k_1$ as required in the theorem is

$$\log \# \bigcup_x S_x \stackrel{+}{>} k_1 + k_2 - 2.2\log(k_1 + k_2). \tag{11}$$

Namely, concatenating an arbitrary binary string x with $K(x) \stackrel{+}{<} k_1$ and an arbitrary string v with $K(v) \stackrel{+}{<} k_2$ we can form $y = xv$ and we have $K(y|x) \stackrel{+}{<} K(v) \stackrel{+}{<} k_2$. This includes every x with $l(x) \stackrel{+}{<} k_1 - 1.1\log k_1$ and every v with $l(v) \stackrel{+}{<} k_2 - 1.1\log k_2$. For appropriate additive constants in $\stackrel{+}{<}$ it will be true that for every such x, all such strings y will belong to S_x.

Choose an arbitrary recursive function R satisfying the statements of the theorem and Equation 10. For each possible value c of $f(y)$ (where $f(y) := R(k_1, k_2, m, y)$), let

$$Y_c := \{\, y : f(y) = c \,\}.$$

Because the number of y's is lower-bounded by Equation 11 and the size of $f(y)$ is upper-bounded by $l(f(y)) \stackrel{+}{<} k_2$ there is a c such that

$$\log \# Y_c \stackrel{+}{>} k_1 - 2.2\log(k_1 + k_2). \tag{12}$$

Let l be the first such c found when enumerating all the sets Y_c. This enumeration can be done as follows: Using k_1 we enumerate all x with $K(x) \leq k_1$ by running all programs of length $\leq k_1$ in rounds of one step per program; when a program halts its output is the next x enumerated. For all of the enumerated x's, we use k_2 to enumerate all y's with $K(y|x) \leq k_2$ in a similar fashion. Finally, for each enumerated y compute $f(y) = R(k_1, k_2, m, y)$ and enumerate the Y_c's.

Therefore, given the recursive function R, the integers k_1, k_2, m, and an constant-length program we can enumerate the Y_c's, determine l, and enumerate Y_l. We can describe R by a constant-length self-delimiting program and the integers k_1, k_2, m by a self-delimiting program $\mu := \lambda_3(k_1)\lambda_3(k_2)\lambda_3(m)$ with λ_3 as in Definition 2. Then, for every i such that y_i is the i-th element in this enumeration of Y_l:

$$\begin{aligned} K(y_i) &\stackrel{+}{<} l(\mu) + \log i + 1.1\log\log i \\ &\stackrel{+}{<} l(m) + \log i + 4.4\log(k_1 + k_2). \end{aligned}$$

If

$$\log i < k_2 - l(m) - 4.5 \log(k_1 + k_2) \tag{13}$$

and $k_1 + k_2$ is large enough, then for every x we have

$$K(y_i|x) \leq K(y_i) + O(1) \leq k_2.$$

Let $t = \min\{k_1, k_2 - l(m)\}$. By Equations 12, 13, for every x there are at least

$$2^{t - 4.5 \log(k_1 + k_2)}$$

values of i with $K(y_i|x) \leq k_2$. Then, for every x there must be at least one of these y_i's, say y, that satisfies

$$K(y|x, f(y), m) \geq t - 4.5 \log(k_1 + k_2).$$

This follows trivially by counting the number of programs of length less than $t - 4.5 \log(k_1 + k_2)$. Hence, by the property $b \geq K(y|x, f(y), m)$ assumed in the statement of the theorem:

$$b \geq \min\{k_1, k_2 - l(m)\} - 4.5 \log(k_1 + k_2).$$

If $k_1 < k_2 - l(m)$ then this contradicts 8, otherwise it contradicts 10. □

4. Cognitive Distance

Let us identify digitized black-and-white pictures with binary strings. There are many distances defined for binary strings. For example, the Hamming distance and the Euclidean distance. Such distances are sometimes appropriate. For instance, if we take a binary picture, and change a few bits on that picture, then the changed and unchanged pictures have small Hamming or Euclidean distance, and they do look similar. However, this is not always the case. The positive and negative prints of a photo have the largest possible Hamming and Euclidean distance, yet they look similar to us. Also, if we shift a picture one bit to the right, again the Hamming distance may increase by a lot, but the two pictures remain similar. Many approaches to pattern recognition try to define pattern similarities with respect to pictures, language sentences, vocal utterances, and so on. Here we assume that similarities between objects can be represented by effectively computable functions (or even upper semicomputable functions) of binary strings. This seems like a minimal prerequisite for machine pattern recognition and physical cognitive processes in general. Let us show that the distance E_1 defined above is, in a sense, minimal among all such reasonable similarity measures.

For a cognitive similarity metric the metric requirements do not suffice: a distance measure like $D(x, y) = 1$ for all $x \neq y$ must be excluded. For each x and d, we want only finitely many elements y at a distance d from x. Exactly how fast we want the distances of the strings y from x to go to ∞ is not important: it is only a matter of scaling. In analogy with Hamming distance in the space of binary sequences, it seems natural to require that there should not be more than 2^d strings y at a distance d from x. This would be a different requirement for each d. With prefix complexity, it turns out to be more convenient to replace this double series of requirements (a different one for each x and d) with a single requirement for each x:

$$\sum_{y: y \neq x} 2^{-D(x,y)} < 1.$$

We call this the *normalization property* since a certain sum is required to be bounded by 1.

We consider only distances that are computable in some broad sense. This condition will not be seen as unduly restrictive. As a matter of fact, only upper semicomputability of $D(x, y)$ will be required. This is reasonable: as we have more and more time to process x

and y we may discover more and more similarities among them, and thus may revise our upper bound on their distance. The upper semicomputability means exactly that $D(x,y)$ is the limit of a computable sequence of such upper bounds.

Definition 4.1. An *admissible distance* $D(x,y)$ is a total nonnegative function on the pairs x,y of binary strings that is 0 if and only if $x = y$, is symmetric, satisfies the triangle inequality, is upper semicomputable and normalized, that is, it is an upper semicomputable, normalized, metric. An admissible distance $D(x,y)$ is *universal* if for every admissible distance $D'(x,y)$ we have $D(x,y) \stackrel{+}{<} D'(x,y)$.

The following theorem shows that E_1 is a universal (that is, optimal) admissible distance. We find it remarkable that this distance happens to also have a "physical" interpretation as the approximate length of the conversion program of Theorem 1, and, as shown in the next section, of the smallest program that transforms x into y on a reversible machine.

Theorem 4. *For an appropriate constant c, let $E(x,y) = E_1(x,y) + c$ if $x \neq y$ and 0 otherwise. Then $E(x,y)$ is a universal admissible metric. That is, it is an admissible distance and it is minimal in the sense that for every admissible distance $D(x,y)$ we have*

$$E(x,y) \stackrel{+}{<} D(x,y).$$

Proof. The nonnegativity and symmetry properties are immediate from the definition. To prove the triangle inequality, let x,y,z be given and assume, without loss of generality, that $E_1(x,z) = K(z|x)$. Then, by the self-delimiting property (or, the easy direction of the addition property),

$$\begin{aligned} E_1(x,z) = K(z|x) &\stackrel{+}{<} K(y,z|x) \stackrel{+}{<} K(y|x) + K(z|x,y) \\ &\stackrel{+}{<} K(y|x) + K(z|y) \leq E_1(x,y) + E_1(y,z). \end{aligned}$$

Hence there is a nonnegative integer constant c such that $E_1(x,z) \leq E_1(x,y) + E_1(y,z) + c$. Let this c be the one used in the statement of the theorem, then $E(x,y)$ satisfies the triangle inequality without an additive constant.

For the normalization property, we have

$$\sum_{y:y\neq x} 2^{-E_1(x,y)} \leq \sum_{y:y\neq x} 2^{-K(y|x)} \leq 1.$$

The first inequality follows from the definition of E_1, and the second one follows from 4.

The minimality property follows from the characterization of $K(y|x)$ given after 4. This property says that if $f(x,y)$ is an upper semicomputable function with $\sum_{y:y\neq x} 2^{-f(x,y)} \leq 1$ then $K(y|x) \stackrel{+}{<} f(x,y)$. This implies that for every admissible distance $D(\cdot,\cdot)$ we have both $K(y|x) \stackrel{+}{<} D(x,y)$ and $K(x|y) \stackrel{+}{<} D(y,x)$. □

Remark 4.2. Remark (Universal Cognitive Distance) The universal admissible distance E_1 minorizes *all* admissible distances: if two pictures are d-close under some admissible distance, then they are $\stackrel{+}{<} d$-close under this universal admissible distance. That is, the latter discovers all effective feature similarities or cognitive similarities between two objects: it is the universal cognitive similarity metric. ♢

5. Reversible Computation Distance

Reversible models of computation in which the transition function is one-to-one have been explored especially in connection with the question of the thermodynamic limits of computation. Reversible Turing machines were introduced by Lecerf [18], and independently but much later by Bennett [3, 4]. Further results concerning them can be found in [4, 5, 19, 20].

Consider the standard model of Turing machine. The elementary operations are rules in quadruple format (p, a, b, q) meaning that a machine in state p scanning symbol a writes a symbol or moves the scanning head one square left, one square right, or not at all (as indicated by b) and enters state q.

Quadruples are said to *overlap in domain* if they cause the machine in the same state and scanning the same symbol to perform different actions. A *deterministic Turing machine* is defined as a Turing machine with quadruples that pairwise do not overlap in domain.

Now consider a special format (deterministic) Turing machines using quadruples of two types: *read/write* quadruples and *move* quadruples. A read/write quadruple (p, a, b, q) causes the machine in state p scanning tape symbol a to write symbol b and enter state q. A move quadruple $(p, \perp, \sigma, q)$ causes the machine in state p to move its tape head by $\sigma \in \{-1, 0, +1\}$ squares and enter state q, oblivious to the particular symbol in the currently scanned tape square. (Here "-1" means "one square left," "0" means "no move" and "$+1$" means "one square right.") Quadruples are said to *overlap in range* if they cause the machine to enter the same state and either both write the same symbol or (at least) one of them moves the head. Said differently, quadruples that enter the same state overlap in range unless they write different symbols. A *reversible Turing machine* is a deterministic Turing machine with quadruples that pairwise do not overlap in range. A k-tape reversible Turing machine uses $(2k + 2)$ tuples that for each tape separately, select a read/write or move on that tape. Moreover, every pair of tuples having the same initial state must specify differing scanned symbols on at least one tape (to guarantee non-overlapping domains), and every pair of tuples having the same final state must write differing symbols on at least one tape (to guarantee non-overlapping ranges).

To show that each partial recursive function can be computed by a reversible Turing machine one can proceed as follows. Take the standard irreversible Turing machine computing that function. We modify it by adding an auxiliary storage tape called the "history tape." The quadruple rules are extended to 6-tuples to additionally manipulate the history tape. To be able to reversibly undo (retrace) the computation deterministically, the new 6-tuple rules have the effect that the machine keeps a record on the auxiliary history tape consisting of the sequence of quadruples executed on the original tape. Reversibly undoing a computation entails also erasing the record of its execution from the history tape.

This notion of reversible computation means that only one-to-one recursive functions can be computed. To reversibly simulate t steps of an irreversible computation from x to $f(x)$ one reversibly computes from input x to output $\langle x, f(x)\rangle$. Say this takes $t' = O(t)$ time. Since this reversible simulation at some time instant has to record the entire history of the irreversible computation, its space use increases linearly with the number of simulated steps t. That is, if the simulated irreversible computation uses s space, then for some constant $c > 1$ the simulation uses $t' \approx c + ct$ time and $s' \approx c + c(s + t)$ space. After computing from x to $f(x)$ the machine reversibly copies $f(x)$, reversibly undoes the computation from x to $f(x)$ erasing its history tape in the process, and ends with one copy of x and one copy of $f(x)$ in the format $\langle x, f(x)\rangle$ and otherwise empty tapes.

Let ψ_i be the partial recursive function computed by the i'th such *reversible Turing machine*. We let ϕ_i denote the partial recursive function computed by the i'th ordinary (in general irreversible) Turing machine. Among the more important properties of reversible Turing machines are the following [4, 5, 19]:

Universal reversible machine: There is a universal reversible machine, i.e. an index u such that for all k and x, $\psi_u(\langle k, x\rangle) = \langle k, \psi_k(x)\rangle$.

Irreversible to reversible: Two irreversible algorithms, one for computing y from x and the other for computing x from y, can be efficiently combined to obtain a reversible algorithm for computing y from x. More formally, for any two indices i and j one can effectively obtain an index k such that, for any strings x and y, if $\phi_i(x) = y$ and $\phi_j(y) = x$, then $\psi_k(x) = y$.

Saving input copy: ¿From any index i one may obtain an index k such that ψ_k has the same domain as ϕ_i and, for every x, $\psi_k(x) = \langle x, \phi_i(x)\rangle$. In other words, an arbitrary Turing machine can be simulated by a reversible one which saves a copy of the irreversible machine's input in order to assure a global one-to-one mapping.

Efficiency: The above simulation can be performed rather efficiently. In particular, for any $\epsilon > 0$ one can find a reversible simulating machine which runs in time $O(T^{1+\epsilon})$ and space $O(S\log(T/S))$ compared to the time T and space S of the irreversible machine being simulated.

One-to-one functions: From any index i one may effectively obtain an index k such that if ϕ_i is one-to-one, then $\psi_k = \phi_i$. The reversible Turing machines $\{\psi_k\}$, therefore, provide a Gödel-numbering of all one-to-one partial recursive functions.

The connection with thermodynamics comes from the fact that in principle the only thermodynamically costly computer operations are those that are *logically irreversible*, i.e. operations that map several distinct logical states of the computer onto a common successor, thereby throwing away information about the computer's previous state [16, 3, 11, 4, 20]. The thermodynamics of computation is discussed further in Section 8. Here we show that the minimal program size for a reversible computer to transform input x into output y is equal within an additive constant to the size of the minimal conversion string p of Theorem 1.

The theory of reversible minimal program size is conveniently developed using a reversible analog of the universal self-delimiting function (prefix machine) U defined in Section 2.

Definition 5.1. A partial recursive function $F(p, x)$ is called a *reversible self-delimiting function* if

- for each p, $F(p, x)$ is one-to-one as a function of x;
- for each x, $\{\, p : \exists y\, F(p, x) = y \,\}$ is a prefix set;
- for each y, $\{\, p : \exists x\, F(p, x) = y \,\}$ is a prefix set.

Remark 5.2. A referee asked whether the last two of these conditions can be replaced with the single stronger one saying that $\{\, p : \exists x, y\, F(p, x) = y \,\}$ is a prefix set. This does not seem to be the case. ♢

In analogy with Remark 2.4, we can define the notion of a *reversible self-delimiting computation* on a reversible Turing machine. Take a reversible multi-tape Turing machine M with a special semi-infinite read-only tape called the *program tape*. There is now no separate input and output tape, only an input-output tape. At the beginning of the computation, the head of the program tape is on the starting square.

We say that M computes the partial function $F(p,x)$ by a *reversible self-delimiting computation* if for all p and x for which $F(p,x)$ is defined:

- M halts with output $y := F(p,x)$ written on its output tape performing a one-to-one mapping $x \leftrightarrow y$ on the input-output tape under the control of the program p.
- The program tape head scans all of p but never scans beyond the end of p.
- At the end of the computation, the program tape head rests on the starting square. Once it starts moving backward it never moves forward again.
- Any other work tapes used during the computation are supplied in blank condition at the beginning of the computation and must be left blank at the end of the computation.

It can be shown (see the references given above) that a function F is reversible self-delimiting if and only if it can be computed by a reversible self-delimiting computation. Informally, again, we will call a reversible self-delimiting function also a *reversible self-delimiting (prefix) machine*.

A *universal reversible prefix machine* UR, which is optimal in the same sense of Section 2, can be shown to exist, and the *reversible Kolmogorov complexity* $KR(y|x)$ is defined as

$$KR(y|x) := \min\{\, l(p) : UR(p,x) = y \,\}.$$

In Section 3, it was shown that for any strings x and y there exists a conversion program p, of length at most logarithmically greater than

$$E_1(x,y) = \max\{K(y|x), K(x|y)\}$$

such that $U(p,x) = y$ and $U(p,y) = x$. Here we show that the length of this minimal such conversion program is equal within a constant to the length of the minimal *reversible* program for transforming x into y.

Theorem 5.

$$KR(y|x) \stackrel{+}{=} \min\{\, l(p) : U(p,x) = y,\ U(p,y) = x \,\}.$$

Proof. ($\stackrel{+}{>}$) The minimal reversible program for y from x, with constant modification, serves as a program for y from x for the ordinary irreversible prefix machine U, because reversible prefix machines are a subset of ordinary prefix machines. We can reverse a reversible program by adding an $O(1)$ bit prefix program to it saying "reverse the following program." Therefore, the reverse of the minimal reversible program for y from x is a minimal reversible program for x from y up to $O(1)$ bits. Hence the minimal reversible program for y from x, with (possibly different) constant modification, serves also as a program for x from y for the ordinary irreversible prefix machine U. Given an input x' and a combination of a program and its reverse we can still be in the situation that the program computes in one direction from some y' to x' and in the other direction from x' to some y''. To have a reversible program that computes between x and y in both directions we need to distinguish between x and y. With x', y', y'' as above we add an $O(1)$-bit prefix program that for input x' states whether the computation is from x' to y' or from x' to y'', expressed in the order of x', y', y'' as in the proof of Theorem 2.

($\stackrel{+}{<}$) The proof of the other direction is an example of the general technique for combining two irreversible programs, for y from x and for x from y, into a single reversible program for y from x. In this case the two irreversible programs are the same, since by Theorem 1 the minimal conversion program p is both a program for y given x and a program for x given y. The computation proceeds by several stages as shown in Figure 1. To illustrate

STAGE AND ACTION	PROGRAM		WORK TAPE	
0. Initial configuration	p̂rog	x		
1. Compute y, saving history	prog̊	y	$(y\|x)$-history	
2. Copy y to blank region	prog̊	y	$(y\|x)$-history	y
3. Undo comp. of y from x	p̂rog	x		y
4. Swap x and y	p̂rog	y		x
5. Compute x, saving history	prog̊	x	$(x\|y)$-history	x
6. Cancel extra x	prog̊	x	$(x\|y)$-history	
7. Undo comp. of x from y	p̂rog	y		

FIGURE 1. Combining irreversible computations of y from x and x from y to achieve a reversible computation of y from x

motions of the head on the self-delimiting program tape, the program p is represented by the string "prog" in the table, with the head position indicated by a caret.

Each of the stages can be accomplished without using any many-to-one operations.

In stage 1, the computation of y from x, which might otherwise involve irreversible steps, is rendered reversible by saving a history, on previously blank tape, of all the information that would have been thrown away.

In stage 2, making an extra copy of the output onto blank tape is an intrinsically reversible process, and therefore can be done without writing anything further in the history. Stage 3 exactly undoes the work of stage 1, which is possible because of the history generated in stage 1.

Perhaps the most critical stage is stage 5, in which x is computed from y for the sole purpose of generating a history of that computation. Then, after the extra copy of x is reversibly disposed of in stage 6 by cancelation (the inverse of copying onto blank tape), stage 7 undoes stage 5, thereby disposing of the history and the remaining copy of x, while producing only the desired output y.

Not only are all its operations reversible, but the computations from x to y in stage 1 and from y to x in stage 5 take place in such a manner as to satisfy the requirements for a reversible prefix interpreter. Hence, the minimal irreversible conversion program p, with constant modification, can be used as a reversible program for UR to compute y from x. This establishes the theorem. □

Definition 5.3. The *reversible distance* $E_2(x,y)$ between x and y is defined by

$$E_2(x,y) := KR(y|x) = \min\{\, l(p) : UR(p,x) = y \,\}.$$

As just proved, this is within an additive constant of the size of the minimal conversion program of Theorem 1. Although it may be logarithmically greater than the optimal distance E_1, it has the intuitive advantage of being the actual length of a concrete program for passing in either direction between x and y. The optimal distance E_1 on the other hand is defined only as the greater of two one-way program sizes, and we don't know whether it corresponds to the length of any two-way translation program.

$E_2(x,y)$ may indeed be legitimately called a distance because it is symmetric and obeys the triangle inequality to within an additive constant (which can be removed by the additive rescaling technique used in the proof of Theorem 4).

Theorem 6.

Stage and Action	Program tape	Work Tape	
0. Initial configuration	p̂progqprog	x	
1. Compute $(y\|x)$, transcribing pprog.	p̂progqprog	y	pprog
2. Space forward to start of qprog.	pprogq̂prog	y	pprog
3. Compute $(z\|y)$.	pprogq̂prog	z	pprog
4. Cancel extra pprog as head returns.	p̂progqprog	z	

FIGURE 2. Reversible execution of concatenated programs for $(y|x)$ and $(z|y)$ to transform x into z.

$$E_2(x,z) \stackrel{+}{<} E_2(x,y) + E_2(y,z)$$

Proof. We will show that, given reversible *UR* programs p and q, for computing $(y|x)$ and $(z|y)$ respectively, a program of the form spq, where s is a constant supervisory routine, serves to compute z from x reversibly. Because the programs are self-delimiting, no punctuation is needed between them. If this were an ordinary irreversible U computation, the concatenated program spq could be executed in an entirely straightforward manner, first using p to go from x to y, then using q to go from y to z. However, with reversible *UR* programs, after executing p, the head will be located at the beginning of the program tape, and so will not be ready to begin reading q. It is therefore necessary to remember the length of the first program segment p temporarily, to enable the program head to space forward to the beginning of q, but then cancel this information reversibly when it is no longer needed.

A scheme for doing this is shown in Figure 2, where the program tape's head position is indicated by a caret. To emphasize that the programs p and q are strings concatenated without any punctuation between them, they are represented respectively in the table by the expressions "pprog" and "qprog", and their concatenation pq by "pprogqprog".

Notice that transcribing "pprog" in stage 1 is straightforward: as long as the program tape head moves forward such a transcription will be done; according to our definition of reversible self-delimiting computation above, this way the whole program will be transcribed.

□

6. SUM DISTANCE

Only the irreversible erasures of a computation need to dissipate energy. This raises the question of the minimal amount of irreversibility required in transforming string x into string y, that is, the number of bits we have to add to x at the beginning of a reversible computation from x to y, and the number of garbage bits left (apart from y) at the end of the computation that must be irreversibly erased to obtain a "clean" y.

The reversible distance E_2 defined in the previous section, is equal to the length of a "catalytic" program, which allows the interconversion of x and y while remaining unchanged itself. Here we consider noncatalytic reversible computations which consume some information p besides x, and produce some information q besides y.

Even though consuming and producing information may seem to be operations of opposite sign, we can define a distance $E_3(\cdot,\cdot)$ based on the notion of information flow, as the minimal *sum* of amounts of extra information flowing into and out of the computer in the course of the computation transforming x into y. This quantity measures the number of irreversible bit operations in an otherwise reversible computation. The resulting distance

turns out to be within a logarithmic additive term of the sum of the conditional complexities $K(y|x) + K(x|y)$. See [20] for a more direct proof than the one provided here, and for a study of resource-limited (for example with respect to time) measures of the number of irreversible bit operations. For our treatment here it is crucial that computations can take unlimited time and space and therefore $E_3(\cdot,\cdot)$ represents a limiting quantity that cannot be realized by feasible computation. For a function F computed by a reversible Turing machine, define

$$E_F(x,y) := \min\{\, l(p) + l(q) : F(\langle p, x\rangle) = \langle q, y\rangle \,\}.$$

Remark 6.1. Since p will be consumed it would be too awkward and not worth the trouble to try to extend the notion of self-delimiting for this case; so, the computations we consider will not be self-delimiting over p. ♢

It follows from the existence of universal reversible Turing machines mentioned in Section 5 that there is a universal reversible Turing machine UR' (not necessarily self-delimiting) such that for all functions F computed on a reversible Turing machine, we have

$$E_{UR'}(x,y) \leq E_F(x,y) + c_F$$

for all x and y, where c_F is a constant which depends on F but not on x or y.

Remark 6.2. In our definitions we have pushed all bits to be irreversibly provided to the start of the computation and all bits to be irreversibly erased to the end of the computation. It is easy to see that this is no restriction. If we have a computation where irreversible acts happen throughout the computation, then we can always mark the bits to be irreversibly erased, waiting with actual erasure until the end of the computation. Similarly, the bits to be provided can be provided (marked) at the start of the computation while the actual reading of them (simultaneously unmarking them) takes place throughout the computation.

By Landauer's principle, which we meet in Section 8, the number of irreversible bit erasures in a computation gives a lower bound on the unavoidable energy dissipation of the computation, each bit counted as $kT\ln 2$, where k is Boltzmann's constant and T the absolute temperature in degrees Kelvin. It is easy to see (proof of Theorem 7) that the minimal number of garbage bits left after a reversible computation going from x to y is about $K(x|y)$ and in the computation from y to x it is about $K(y|x)$. ♢

Definition 6.3. We fix a universal reference reversible Turing machine UR'. The *sum distance* $E_3(x,y)$ is defined by

$$E_3(x,y) := E_{UR'}(x,y).$$

Theorem 7.

$$E_3(x,y) = K(x|y) + K(y|x) + O(\log K(x,y)).$$

Proof. ($\geq$) We first show the lower bound $E_3(x,y) \geq K(y|x) + K(x|y)$. Let us use the universal prefix machine U of Section 2. Due to its universality, there is a constant-length binary string r such that for all p, x we have

$$U(r\lambda_2(p), x) = \langle UR'(\langle p, x\rangle)\rangle_2$$

(The function λ_2 in Definition 2 makes p self-delimiting. Recall that $\langle\cdot,\cdot\rangle_2$ selects the second element of the pair.) Suppose $UR'(\langle p, x\rangle) = \langle q, y\rangle$. Then it follows that $y = U(r\lambda_2(p), x)$, hence

$$K(y|x) \stackrel{+}{<} l(r\lambda_2(p)) \stackrel{+}{<} l(\lambda_2(p)) \stackrel{+}{<} l(p) + 2\log l(p).$$

Since the computation is reversible, the garbage information q at the end of the computation yielding $\langle y, q\rangle$ serves the rôle of program when we reverse the computation to compute x from y. Therefore, we similarly have $K(x|y) \stackrel{+}{<} l(q) + 2\log l(q)$, which finishes the proof of the lower bound.

($\leq$) Let us turn to the upper bound and assume $k_1 = K(x|y) \leq k_2 = K(y|x)$ with $l = k_2 - k_1 \geq 0$. According to Theorem 1, there is a string d of length l such that $K(xd|y) \stackrel{+}{=} k_1 + K(k_1, k_2)$ and $K(y|xd) \stackrel{+}{=} k_1 + K(k_1, k_2)$. According to Theorem 1 and Theorem 5 there is a self-delimiting program q of length $\stackrel{+}{=} k_1 + K(k_1, k_2)$ going reversibly between xd and y. Therefore with a constant extra program s, the universal reversible machine will go from qxd to qy. And by the above estimates

$$l(qd) + l(q) \stackrel{+}{<} 2k_1 + l + 2K(k_1, k_2) = k_1 + k_2 + O(\log k_2).$$

□

Note that all bits supplied in the beginning to the computation, apart from input x, as well as all bits erased at the end of the computation, are *random* bits. This is because we supply and delete only shortest programs, and a shortest program q satisfies $K(q) \geq l(q)$, that is, it is maximally random.

Remark 6.4. It is easy to see that up to an additive logarithmic term the function $E_3(x, y)$ is a metric on $\{0, 1\}^*$; in fact it is an admissible (cognitive) distance as defined in Section 4. ♢

7. Relations Between Information Distances

The metrics we have considered can be arranged in increasing order. As before, the relation $\stackrel{\log}{<}$ means inequality to within an additive $O(\log)$, and $\stackrel{\log}{=}$ means $\stackrel{\log}{<}$ and $\stackrel{\log}{>}$.

$$\begin{aligned} E_1(x, y) &= \max\{K(y|x), K(x|y)\} \\ &\stackrel{\log}{=} E_2(x, y) = KR(y|x) \\ &\stackrel{+}{=} E_0(x, y) = \min\{\, l(p) : U(p, x) = y,\ U(p, y) = x \,\} \\ &\stackrel{\log}{<} K(x|y) + K(y|x) \stackrel{\log}{=} E_3(x, y) \\ &\stackrel{\log}{<} 2E_1(x, y). \end{aligned}$$

The sum distance E_3, is tightly bounded between the optimum distance E_1 and twice the optimal distance. The lower bound is achieved if one of the conditional complexities $K(y|x)$ and $K(x|y)$ is zero, the upper bound is reached if the two conditional complexities are equal.

It is natural to ask whether the equality $E_1(x, y) \stackrel{\log}{=} E_2(x, y)$ can be tightened. We have not tried to produce a counterexample but the answer is probably no.

8. Thermodynamic Cost

Thermodynamics, among other things, deals with the amounts of heat and work ideally required, by the most efficient process, to convert one form of matter to another. For example, at 0 C and atmospheric pressure, it takes 80 calories of heat and no work to convert a gram of ice into water at the same temperature and pressure. From an atomic point of view, the conversion of ice to water at 0 C is a reversible process, in which each melting

water molecule gains about 3.8 bits of entropy (representing the approximately $2^{3.8}$-fold increased freedom of motion it has in the liquid state), while the environment loses 3.8 bits. During this ideal melting process, the entropy of the universe remains constant, because the entropy gain by the ice is compensated by an equal entropy loss by the environment. Perfect compensation takes place only in the limit of slow melting, with an infinitesimal temperature difference between the ice and the water.

Rapid melting, e.g. when ice is dropped into hot water, is thermodynamically irreversible and inefficient, with the the hot water losing less entropy than the ice gains, resulting in a net and irredeemable entropy increase for the combined system. (Strictly speaking, the microscopic entropy of the universe as a whole does not increase, being a constant of motion in both classical and quantum mechanics. Rather what happens when ice is dropped into hot water is that the marginal entropy of the (ice + hot water) system increases, while the entropy of the universe remains constant, due to a growth of mutual information mediated by subtle correlations between the (ice + hot water) system and the rest of the universe. In principle these correlations could be harnessed and redirected so as to cause the warm water to refreeze, but in practice the melting is irreversible.)

Turning again to ideal reversible processes, the entropy change in going from state X to state Y is an anti-symmetric function of X and Y; thus, when water freezes at 0 C by the most efficient process, it gives up 3.8 bits of entropy per molecule to the environment. When more than two states are involved, the entropy changes are transitive: thus the entropy change per molecule of going from ice to water vapor at 0 C ($+32.6$ bits) plus that for going from vapor to liquid water (-28.8 bits) sum to the entropy change for going from ice to water directly. Because of this asymmetry and transitivity, entropy can be regarded as a thermodynamic potential or state function: each state has an entropy, and the entropy change in going from state X to state Y by the most efficient process is simply the entropy difference between states X and Y.

Thermodynamic ideas were first successfully applied to computation by Landauer. According to *Landauer's principle* [16, 4, 26, 27, 6] an operation that maps an unknown state randomly chosen from among n equiprobable states onto a known common successor state must be accompanied by an entropy increase of $\log_2 n$ bits in other, non-information-bearing degrees of freedom in the computer or its environment. At room temperature, this is equivalent to the production of $kT \ln 2$ (about $7 \cdot 10^{-22}$) calories of waste heat per bit of information discarded.

The point here is the change from "ignorance" to "knowledge" about the state, that is, the gaining of information and not the erasure in itself (instead of erasure one could consider measurement that would make the state known).

Landauer's priniciple follows from the fact that such a logically irreversible operation would otherwise be able to decrease the thermodynamic entropy of the computer's data without a compensating entropy increase elsewhere in the universe, thereby violating the second law of thermodynamics.

Converse to Landauer's principle is the fact that when a computer takes a physical *randomizing* step, such as tossing a coin, in which a single logical state passes stochastically into one of n equiprobable successors, that step can, if properly harnessed, be used to remove $\log_2 n$ bits of entropy from the computer's environment. Models have been constructed, obeying the usual conventions of classical, quantum, and thermodynamic thought-experiments [16, 15, 3, 4] [11, 17, 23, 1, 10] showing both the ability in principle to perform logically reversible computations in a thermodynamically reversible fashion (i.e. with arbitrarily little entropy production), and the ability to harness entropy increases

due to data randomization within a computer to reduce correspondingly the entropy of its environment.

In view of the above considerations, it seems reasonable to assign each string x an effective thermodynamic entropy equal to its Kolmogorov complexity $K(x)$. A computation that erases an n-bit random string would then reduce its entropy by n bits, requiring an entropy increase in the environment of at least n bits, in agreement with Landauer's principle.

Conversely, a randomizing computation that starts with a string of n zeros and produces n random bits has, as its typical result, an algorithmically random n-bit string x, i.e. one for which $K(x) \approx n$. By the converse of Landauer's principle, this randomizing computation is capable of removing up to n bits of entropy from the environment, again in agreement with the identification of the thermodynamic entropy and Kolmogorov complexity.

What about computations that start with one (randomly generated or unknown) string x and end with another string y? By the transitivity of entropy changes one is led to say that the thermodynamic cost, i.e. the minimal entropy increase in the environment, of a transformation of x into y, should be

$$W(y|x) = K(x) - K(y),$$

because the transformation of x into y could be thought of as a two-step process in which one first erases x, then allows y to be produced by randomization. This cost is obviously anti-symmetric and transitive, but is not even semicomputable. Because it involves the *difference* of two semicomputable quantities, it is at best expressible as the *non-monotone* limit of a computable sequence of approximations. Invoking the identity [13] $K(x,y) \stackrel{+}{=} K(x) + K(y|x^*)$, where x^* denotes the first minimal program for x in enumeration order (or equivalently, $x^* := \langle x, K(x)\rangle$), the above cost measure $W(y|x)$ can also be interpreted as a difference in conditional complexities,

$$W(y|x) \stackrel{+}{=} K(x|y^*) - K(y|x^*)\,.$$

Such indirect conditional complexities, in which the input string is supplied as a minimal program rather than directly, have been advocated by Chaitin [7] on grounds of their similarity to conditional entropy in standard information theory.

An analogous anti-symmetric cost measure based on the difference of direct conditional complexities

$$W'(y|x) = K(x|y) - K(y|x).$$

was introduced and compared with $W(x|y)$ by Zurek [26], who noted that the two costs are equal within a logarithmic additive term. Here we note that $W'(y|x)$ is non-transitive to a similar extent.

Clearly, $W'(y|x)$ is tied to the study of distance E_3, the sum of irreversible information flow in and out of the computation. Namely, analysis of the proof of Theorem 7 shows that up to logarithmic additional terms, a necessary and sufficient number of bits of $K(y|x)$ (the program) needs to be supplied at the start of the computation from x to y, while a necessary and sufficient number of bits of $K(x|y)$ (the garbage) needs to be irreversibly erased at the end of the computation. The thermodynamical analysis of Landauer's principle at the beginning of this section says the thermodynamic cost, and hence the attending heat dissipation, of a computation of y from x is given by the number of irreversibly erased bits minus the number of irreversibly provided bits, that is, $W'(y|x)$.

It is known that there exist strings [13] x of each length such that $K(x^*|x) \approx \log l(x)$, where x^* is the minimal program for x. According to the W' measure, erasing such an x via

the intermediate x^* would generate $\log l(x)$ less entropy than erasing it directly, while for the W measure the two costs would be equal within an additive constant. Indeed, erasing in two steps would cost only $K(x|x^*) - K(x^*|x) + K(x^*|0) - K(0|x^*) \stackrel{+}{=} K(x) - K(x^*|x)$ while erasing in one step would cost $K(x|0) - K(0|x) = K(x)$.

Subtle differences like the one between W and W' pointed out above (and resulting in a slight nontransitivity of W') depend on detailed assumptions which must be, ultimately, motivated by physics [27]. For instance, if one were to follow Chaitin [7] and define a *Kc*-complexity as $Kc(x) := K(x), Kc(x,y) := K(x,y)$ but the conditional information $Kc(y|x) := K(y|x^*)$ then the joint information would be given directly by $Kc(x,y) \stackrel{+}{=} Kc(x) + Kc(y|x)$, and the *Kc*-analogues $Wc'(y|x) = Wc(y|x)$ would hold without logarithmic corrections (because $Kc(y|x) = Kc(y|x^*)$). This *Kc* notation is worth considering especially because the joint and conditional *Kc*-complexities satisfy equalities which also obtain for the statistical entropy (i.e. Gibbs-Shannon entropy defined in terms of probabilities) without logarithmic corrections. This makes it a closer analog of the thermodynamic entropy. Moreover—as discussed by Zurek [27], in a cyclic process of a hypothetical Maxwell demon-operated engine involving acquisition of information through measurement, expansion, and subsequent erasures of the records compressed by reversible computation—the optimal efficiency of the cycle could be assured only by assuming that the relevant minimal programs are already available.

These remarks lead one to consider a more general issue of entropy changes in nonideal computations. Bennett [4] and especially Zurek [27] have considered the thermodynamics of an intelligent demon or engine which has some capacity to analyze and transform data x before erasing it. If the demon erases a random-looking string, such as the digits of π, without taking the trouble to understand it, it will commit a thermodynamically irreversible act, in which the entropy of the data is decreased very little, while the entropy of the environment increases by a full n bits. On the other hand, if the demon recognizes the redundancy in π, it can transform π to an (almost) empty string by a reversible computation, and thereby accomplish the erasure at very little thermodynamic cost. See for a comprehensive treatment [22].

More generally, given unlimited time, a demon could approximate the semicomputable function $K(x)$ and so compress a string x to size $K(x)$ before erasing it. But in limited time, the demon will not be able to compress x so much, and will have to generate more entropy to get rid of it. This tradeoff between speed and thermodynamic efficiency is superficially similar to the tradeoff between speed and efficiency for physical processes such as melting, but the functional form of the tradeoff is very different. For typical physical state changes such as melting, the excess entropy produced per molecule goes to zero inversely in the time t allowed for melting to occur. But the time-bounded Kolmogorov complexity $K^t(x)$, i.e. the size of the smallest program to compute x in time less than t, in general approaches $K(x)$ only with uncomputable slowness as a function of t and x. These issues have been analyzed in more detail by two of us in [20].

9. Density Properties

In a discrete space with some distance function, the rate of growth of the number of elements in balls of size d can be considered as a kind of "density" or "dimension" of the space. For all information distances one significant feature is how many objects there are within a distance d of a given object. From the pattern recognition viewpoint such information tells how many pictures there are within the universal admissible (max) distance

$E_1(x,y) = d$. For the reversible distance $E_2(x,y) = d$ this tells us how many objects one can reach using a reversible program of length d. For the sum distance $E_3(x,y) = d$ this tells us how many objects there are within d irreversible bit operations of a given object.

Recall the distances $E_1(x,y) = \max\{K(x|y), K(y|x)\}$ and $E_3(x,y) \stackrel{\log}{=} K(x|y) + K(y|x)$. For a binary string x of length n, a nonnegative number d and $i = 1, 3$, let $B_i(d,x)$ be the set of strings $y \neq x$ with $E_i(x,y) \leq d$, and $B_i(d,x,n) := B_i(d,x) \bigcap \{0,1\}^n$.

The functions $B_i(d,x)$ behave rather simply: $\log \#B_i(d,x)$ grows essentially like d. The functions $B_i(d,x,n)$ behave, however, differently. While $\log \#B_1(d,x,n)$ grows essentially like d, the function $\log \#B_3(d,x,n)$ grows essentially like $d/2$. This follows from the somewhat more precise result in 10 below. First we treat the general case below that says that balls around x of radius d with d random with respect to x contain less elements: *neighborhoods of tough radius's contain less neighbors*.

Theorem 8. *Let x be a binary string of length n. The number of binary strings y with $E_1(x,y) \leq d$ satisfies*

$$\log \#B_1(d,x) \stackrel{+}{=} d - K(d|x);$$
$$d - K(d) \stackrel{+}{<} \log \#B_1(d,x,n) \stackrel{+}{<} d - K(d|x).$$

The last equation holds only for $n \geq d - K(d)$: for $n < d - K(d)$ we have $\log \#B_1(d,x,n) \stackrel{+}{=} n$.

Proof. ($B_1(d,x) \stackrel{+}{<}$) For every binary string x

$$\begin{aligned}\sum_{d=0}^{\infty} \#B_1(d,x) 2^{-d-1} &= \sum_{d=0}^{\infty} \sum_{j=0}^{d} 2^{-d+j-1} \sum_{y: E_1(x,y)=j \& y \neq x} 2^{-j} \\ &= \sum_{d=0}^{\infty} \sum_{j=0}^{d} 2^{-d+j-1} \sum_{y: E_1(x,y)=j \& y \neq x} 2^{-E_1(x,y)} \\ &= \sum_{i=1}^{\infty} 2^{-i} \sum_{y: y \neq x} 2^{-E_1(x,y)} \leq 1,\end{aligned}$$

where the last inequality follows from the properties of $E_1(\cdot,\cdot)$ proven in Theorem 4. Since $f(x,d) := \log(2^{d+1}/\#B_1(d,x))$ is upper semicomputable and satisfies $\sum_d 2^{-f(x,d)} \leq 1$, by Lemma 2.6 we have $K(d|x) \stackrel{+}{<} f(x,d) \stackrel{+}{=} d - \log \#B_1(d,x)$.

($B_1(d,x) \stackrel{+}{>}$) For all $i < 2^{d-K(d|x)}$, consider the strings $y_i = \lambda_3(i)x$ where λ_3 is the self-delimiting code of Definition 2. The number of such strings y_i is $2^{d-K(d|x)}$. Clearly, for every i, we have $K(x|y_i) \stackrel{+}{=} 0$ and $K(y_i|x) \stackrel{+}{=} K(i|x)$. Therefore,

$$E_1(x,y_i) \stackrel{+}{<} K(i|x).$$

Each i can be represented by a string z_i of length precisely $d - K(d|x)$, if necessary by padding it up to this length. Let q be a shortest self-delimiting program computing d from x. By definition $l(q) = K(d|x)$. The program qz_i is a self-delimiting program to compute i from x: Use q to compute d from x and subsequently use $d - l(q) = d - K(d|x) = l(z_i)$ to determine where z_i ends. Hence, $K(i|x) \stackrel{+}{<} l(qz_i) = d$ from which $E_1(x,y_i) \stackrel{+}{<} d$ follows. The implied additive constants in $\stackrel{+}{<}$ can be removed in any of the usual ways.

($B_1(d,x,n) \stackrel{+}{<}$) Since $B_1(d,x,n) \leq B_1(d,x)$ the upper bound on the latter is also an upper bound on the former.

($B_1(d,x,n) \stackrel{+}{>}$ and $n \geq d - K(d)$) For the $d - K(d)$ lower bound on $\log \#B_1(d,x,n)$ the proof is similar but now we consider all $i < 2^{d-K(d)}$ and we choose the strings $y_i = x \oplus i$ where $\oplus$ means bitwise exclusive-or (if $l(i) < n$ then assume that the missing bits are 0's).

($B_1(d,x,n)$ and $n < d - K(d)$) in that case we obtain all strings in $\{0,1\}^n$ as y_i's in the previous proof. □

Note that $K(d) \stackrel{+}{<} \log d + 2 \log\log d$. It is interesting that a similar dimension relation holds also for the larger distance $E_3(x,y) \stackrel{\log}{=} K(y|x) + K(x|y)$.

Theorem 9. *Let x be a binary string. The number $B_3(d,x)$ of binary strings y with $E_3(x,y) \leq d$ satisfies*

$$\log \#B_3(d,x) \stackrel{\log}{=} d - K(d|x).$$

Proof. ($\stackrel{+}{<}$) This follows from the previous theorem since $E_3 \geq E_1$.

($\stackrel{\log}{>}$) Consider strings y of the form px where p is a self-delimiting program. For all such programs, $K(x|y) \stackrel{+}{=} 0$, since x can be recovered from y by a constant-length program. Therefore $E_3(x,y) \stackrel{\log}{=} K(y|x) \stackrel{+}{=} K(p|x)$. Now just as in the argument of the previous proof, there are at least $2^{d-K(d|x)}$ such strings p with $K(p|x) \leq d$. □

The number of strings of length n within any E_3-distance of a *random* string x of length n, (that is, a string with $K(x)$ near n) turns out to be different from the number of strings of length n within the same E_1-distance. In the E_3-distance: "*tough guys have few neighbors of their own size*".

In particular, a random string x of length n has only about $2^{d/2}$ strings of length n within E_3-distance d while there are essentially 2^d such strings within E_1-distance d of x by Theorem 8. Moreover, since Theorem 9 showed that every string has essentially 2^d neighbors altogether in E_3-distance d, for every random string x asymptotically *almost all* its neighbors within E_3-distance d have *length unequal* n. The following theorem describes the general situation.

Theorem 10. *For each x of length n we have*

$$\log \#B_3(d,x,n) \stackrel{\log}{=} \frac{n + d - K(x)}{2},$$

while $n - K(x) \leq d$. (For $n - K(x) > d$ we have $\log \#B_3(d,x,n) \stackrel{\log}{=} d$.)

Proof. Let $K(x) \stackrel{\log}{=} n - \delta(n)$ (for example, $K(x) \stackrel{+}{=} n + K(n) - \delta(n)$.
($\geq$) Let $y = x^*z$ with $l(y) = n$ and $l(z) = \delta(n)$, and let x^* be the first self-delimiting program for x ($l(x^*) = K(x)$) that we find by dovetailing all computations on programs of length less than n. We can retrieve z from y using at most $O(\log n)$ bits. There are $2^{\delta(n)}$ different such y's. For each such y we have $K(x|y) = O(1)$, since x can be retrieved from y using x^*. Now suppose that we also replace the fixed first $l/2$ bits of y by an arbitrary $u \in \{0,1\}^{l/2}$ for some value of l to be determined later. Then, the total number of y's increases to $2^{\delta(n)+l/2}$.

These choices of y must satisfy $E_3(x,y) \leq d$. Clearly, $K(y|x) \stackrel{\log}{<} \delta(n) + l/2$. Moreover, $K(x|y) \stackrel{\log}{<} l/2$ since we can retrieve x by providing $l/2$ bits. Therefore, $K(x|y) + K(y|x) \stackrel{\log}{<} l/2 + \delta(n) + l/2$. Since the left-hand side has value at most d, the largest l we can choose is $l \stackrel{\log}{=} d - \delta(n)$.

This shows that the number $\#B_3(d,x,n)$ of y's such that $E_3(x,y) \leq d$ satisfies

$$\log \#B_3(d,x,n) \stackrel{\log}{>} \frac{\delta(n)+d}{2}.$$

($\leq$) Assume, to the contrary, that there are at least $2^{(d+\delta(n))/2+c}$ elements y of length n such that $E_3(x,y) \leq d$ holds, with c some large constant to be determined later. Then, for some y,

$$K(y|x) \geq \frac{d+\delta(n)}{2} + c.$$

By assumption, $K(x) \stackrel{\log}{=} n - \delta(n)$, $K(y) \stackrel{\log}{<} n$. By the addition theorem 5 we find $n + (d - \delta(n))/2 + c \stackrel{\log}{<} n + K(x|y)$. But this means that

$$K(x|y) \stackrel{\log}{>} \frac{d-\delta(n)}{2} + c,$$

and these two equations contradict $K(x|y) + K(y|x) \leq d$ for large enough $c = O(\log n)$. □

It follows from our estimates that in every set of low Kolmogorov complexity almost all elements are far away from each other in terms of the distance E_1.

If S is a finite set of low complexity (like a finite initial segment of a recursively enumerable set) then almost all pairs of elements in the set have large information distance. Let the Kolmogorov complexity $K(S)$ of a set be the length of a shortest binary program that enumerates S and then halts.

Theorem 11. *For a constant c, let S be a set with $\#S = 2^d$ and $K(S) = c \log d$. Almost all pairs of elements $x, y \in S$ have distance $E_1(x,y) \geq d$, up to an additive logarithmic term.*

The proof of this theorem is easy. A similar statement can be proved for the distance of a string x (possibly outside S) to the majority of elements y in S. If $K(x) \geq n$, then for almost all $y \in S$ we have $E_1(x,y) \geq n + d \pm O(\log dn)$.

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